

# Package ‘rCRM’

November 30, 2018

**Type** Package

**Title** Regularized Continual Reassessment Method

**Version** 0.1

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**Description** Fit a 2-parameter continual reassessment method (CRM) model (O’Quigley and Shen (1996), <doi: 10.2307/2532905>) regularized with L2 norm (Friedman et al. (2010), <doi: 10.18637/jss.v033.i01>) adjusted by the distance with the target dose limiting toxicity (DLT) rate.

**License** GPL (>= 2)

**Encoding** UTF-8

**LazyData** true

**Imports** Rcpp (>= 0.12.19)

**LinkingTo** Rcpp, RcppEigen

**NeedsCompilation** yes

**Repository** CRAN

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rCRM-package

*Regularized CRM*

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**Description**

Fit a 2-parameter CRM model (O'Quigley and Shen 1996) regularized with L2 norm (Friedman et al. 2010) adjusted by the distance with the target DLT rate.

The package uses one-step coordinate descent algorithm and runs extremely fast.

**Details**

Package: rCRM  
Type: Package  
Version: 0.1  
Date: 2018-11-06  
License: GPL (>= 2)

Functions: [rCRM](#)

**Author(s)**

Xiang Li, Hong Tian, Kevin Liu, Pilar Lim  
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**References**

O'Quigley, J., Shen, L.Z. (1996). *Continual reassessment method: a likelihood approach. Biometrics, pp.673-684.*  
Friedman, J., Hastie, T. and Tibshirani, R. (2010). *Regularization paths for generalized linear models via coordinate descent, Journal of Statistical Software, Vol. 33(1), 1.*

**Examples**

```
set.seed(1213)

dose0=c(1:6)
prob0=c(0.007, 0.086, 0.294, 0.545, 0.731, 0.841)

m=3; Y=NULL; X=NULL
for (i in 1:length(dose0)) {
  Y=c(Y, rbinom(m, size=1, prob=prob0[i]))
  X=c(X, rep(i, m))
}
```

```
fiti=rCRM(X, Y, dose0, tp=0.3, mlambda=10)
# attributes(fiti)
```

---

print.rCRM                      *Print a rCRM Object*

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## Description

Print a summary of results

## Usage

```
## S3 method for class 'rCRM'
print(x, digits = 3, ...)
```

## Arguments

x	fitted rCRM object
digits	number of digits in printout
...	additional print arguments

## Details

The performed model is printed, followed by the estimated probability of DLT from a fitted rCRM object.

## Value

The data frame above is silently returned

## Author(s)

Maintainer: Xiang Li <xli256@its.jnj.com>

## See Also

[rCRM](#)

**Examples**

```

set.seed(1213)

dose0=c(1:6)
prob0=c(0.007, 0.086, 0.294, 0.545, 0.731, 0.841)

m=3; Y=NULL; X=NULL
for (i in 1:length(dose0)) {
  Y=c(Y, rbinom(m, size=1, prob=prob0[i]))
  X=c(X, rep(i, m))
}

fiti=rCRM(X, Y, dose0, tp=0.3, mlambda=10)
# attributes(fiti)
fiti

```

rCRM

*Fit a 2-parameter CRM***Description**

Fit a 2-parameter CRM model (O'Quigley and Shen 1996) regularized with L2 norm (Friedman et al. 2010) adjusted by the distance with the target DLT rate.

**Usage**

```

rCRM(x, y, dose0, tp = 0.3, family = "2P", mlambda = 1, nlambda = 50, rlambda = NULL,
wldose = NULL, nfolds = length(y), foldid = NULL, keep.beta = FALSE,
thresh = 1e-07, maxit = 1e+04, threshP = 1e-06, threshB = 100)

```

**Arguments**

x	input vector of dose.
y	response variable. y is a binary vector with 0 (not DLT) and 1 (DLT).
dose0	dose regimen. x should be included in dose0.
tp	target toxicity probability. Default is 0.3.
family	type of CRM models. Now only supports 2-parameter CRM, 2P.
mlambda	maximum of tuning parameter lambda. The optimal lambda is selected by cross-validation.
nlambda	number of lambda values. Default is 50.
rlambda	fraction of mlambda to determine the smallest value for lambda. The default is rlambda = 0.0001 when the number of observations is larger than or equal to the number of variables; otherwise, rlambda = 0.01.
wldose	penalty weights used with L2 norm (adaptive L2). The wldose is a vector of non-negative values with the same length as dose0. Default is NULL indicating that weights are calculated based on MLE.

<code>nfolds</code>	number of folds. With <code>nfolds = 1</code> and <code>foldid = NULL</code> , cross-validation is not performed. For cross-validation, smallest value allowable is <code>nfolds = 3</code> . Specifying <code>foldid</code> overrides <code>nfolds</code> . Default is <code>nfolds=length(y)</code> indicating leave-one-out cross-validation.
<code>foldid</code>	an optional vector of values between 1 and <code>nfolds</code> specifying which fold each observation is in. Default is <code>foldid=NULL</code> .
<code>keep.beta</code>	logical flag for returning estimates for all <code>lambda</code> values. For <code>keep.beta = FALSE</code> , only return the estimate with the minimum cross-validation value.
<code>thresh</code>	convergence threshold for coordinate descent. Default value is <code>1E-7</code> .
<code>maxit</code>	maximum number of iterations for coordinate descent. Default is <code>1E+4</code> .
<code>threshP</code>	boundary for calculating the probability of DLT. Default is <code>1E-6</code> . The estimated probability is truncated between <code>1E-6</code> and <code>1-1E-6</code> .
<code>threshB</code>	boundary for calculating the parameters. Default is <code>100</code> . The estimates are truncated between <code>-100</code> and <code>100</code> .

### Details

One-step coordinate descent algorithm is applied for each `lambda`. Cross-validation is used for tuning parameters.

### Value

An object with S3 class "rCRM".

<code>Beta</code>	estimates in 2-parameter CRM model.
<code>fit</code>	a data.frame containing <code>lambda</code> and proportion of deviance. With cross-validation, additional results are reported, such as average cross-validation likelihood <code>cvm</code> and its standard error <code>cvse</code> , and <code>index</code> with '*' indicating the minimum <code>cvm</code> .
<code>lambda.min</code>	value of <code>lambda</code> that gives minimum <code>cvm</code> .
<code>flag</code>	convergence flag (for internal debugging). <code>flag = 0</code> means converged.
<code>prob</code>	estimated probability of DLT at each <code>dose0</code> .
<code>dose.close</code>	the index of dose in <code>dose0</code> with the <code>prob</code> closest to <code>tp</code> .
<code>family</code>	type of CRM models. <code>2P</code> is 2-parameter CRM model.

### Warning

It may terminate and return `NULL`.

### Author(s)

Maintainer: Xiang Li <xli256@its.jnj.com>

## References

- O'Quigley, J., Shen, L.Z. (1996). *Continual reassessment method: a likelihood approach. Biometrics*, 673-684.
- Friedman, J., Hastie, T. and Tibshirani, R. (2010). *Regularization paths for generalized linear models via coordinate descent, Journal of Statistical Software, Vol. 33(1), 1.*

## Examples

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}

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# attributes(fiti)
```

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